

Ziegler–Nichols Based Intelligent Controller Design of a SPM System to
Reduce the Hysteresis Effect of Force Actuator

林君明, 張博光

Communication Engineering

Engineering

jmlin@chu.edu.tw

Abstract

This research applied Ziegler–Nichols based PID controller design method to the intelligent fuzzy PID controller design of a Scanning Probe Microscope (SPM) system, thus the relative stability can be reserved. In addition, one can see the hysteresis and parameters variation effects of the force actuator can be reduced. This improvement had been verified by practical implementation. Comparing the results with the design with the Ziegler–Nichols based PID controller, one can see that the proposed system is more robust.

Keyword : PID