3D Model Retrieval Using 2D Cepstral Features 李建興, 石昭玲, 周智勳, 游坤明, 洪雋彥
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Abstract

In this paper, we will propose a 3D model retrieval approach using 2D cepstral features. First, six projection planes representing the elevation (depth) value are generated. Then, 2D cepstral features are extracted from each projection plane for searching similar 3D models. Experiments conducted on the Princeton Shape Benchmark (PSB) database have shown that the proposed 2D cepstral features outperforms other state-of-the-art descriptors in terms of the DCG score.

Keyword: 3D model retrieval, 2D cepstral feature